

Troubleshooting Guide

Spray King[®] Water Tank

Models SK-5-AT/SK-6-AT SK-8-AT SK-9-AT

Troubleshooting

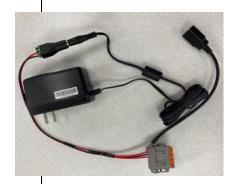
Troubleshooting Issue & Steps	Values	Results
1. Screen Does Not Power On		
a. Check Fuses There are two fuses located on the outside of the right side of the cab, behind the outer access panel.		Test fuses. If fuses are bad, replace. If fuses are OK, proceed to b.
DEM		
b. Check Power Circuits Check power to screen. On 12 pin Deutz plug there are two 24 volt power circuits. Pin 1 is a solid red wire; Pin 3 is a red wire with white stripe.		Test for power. If power circuits are OK, proceed to c.
c. Check Ground Circuit The ground circuit to the screen is a W25 black wire. There should be continuity to the chassis ground.		If circuits OK, move to d.

Troubleshooting Issue & Steps Values Results

After testing, if screen still does not power on, replace screen.

d. Bench Test Screen

Bench test the screen using a 110 voltage adaptor test harness, part number WH10189 (pictured). If screen powers on there is a connection problem. Check Deutz connector for broken pins or bad connection to plug.



2. Screen is on, but no function of spray heads and other optional accessories

For Spray King tanks with a Crossfire Controller (pre-2022). For Spray King from 2022 with the IMF Controller, refer to Section VIII of the Appendix of this guide.

a. Check for blink codes

Check Crossfire controller mounted on underside of rear of water tank frame rail. Light will flash green and red when key if first turned on. During this time the screen is setting up programming in Crossfire for options setup from script file (see below).

After 30 seconds the light should go solid green.

If the red light flashes, refer to blink code status.



Troubleshooting Issue & Steps	Values	Results
Crossfire Status LED	Indicators	
RED Codes		
CANopen mode	State	Blinking Pattern
CAN Bus Off	LED ON	Constantly ON
CAN Bus Warning	LED Single Flash	Iso-phase on and off wth a frequency of approximately 2.5 Hz: (ON 200ms, OFF 200 ms)
Output Port Error	LED Blinking	Iso-phase on and off with a frequency of approximately 2.5 Hz: (ON 200ms, OFF 200ms) The red error blinking is only shown during interleaving 2.5 second intervals.
GREEN Codes		
CANopen mode	State	Blinking Pattern
Operational Pre-Operational	LED ON	Contantly ON
Initializing	LED Blinking	One short flash: (ON 200 ms, OFF 1000 ms)
Stopped	LED Single Flash	One short flash: (ON 200 ms, OFF 1000 ms)
o. Solid Red Lamp Signal A solid red lamp is a can bus fail	ure.	Continuity checks must be made on can bus From screen 12 pin connector to Crossfire 3 pin amp seal connector. Check yellow wire in pin 7 on screen plug to yellow wire on Crossfire connector pin 32. Check green wire on pin 18 to pin 33. If both circuits are OK, check the resistors.
Can bus circuit: N39 Yellow wire N40 Green wire		There are two 120 ohm resistors, one accessible at cab screen harness end, the other at Crossfire tank harness end.
		Remove each Delphi connector and check f 120 ohms resistance.
		If resistors are OK, repair bad connection in harness.

Troubleshooting Issue & Steps	Values	Results
c. Single (Slow) Flash Red Signal This is a can bus warning This is always caused by a bad connection or pins pushed back in connector. There is a possible bad crimp on terminal pins in connectors.		Locate, perform pull test on each circuit at all connectors – screen cab to tank, bulkhead, and Crossfire connector. Gently pull each wire to ensure crimp and pin are secure and locked in place. Check for pinched or cut wires.
d. Multiple Flashing (Fast) Red Signal This is an output error. Open door to hydraulic control box. Depending on model, there will be 4 to 6 electric hydraulic solenoids. With the key on, there should be one LED light on for each solenoid. This indicates power and ground are good. If one or more lights are out, there is a break in the circuit.		Ohm test across positive and negative terminals on hydraulic solenoid valves with connector removed. Ohm range should be 17 to 19 ohms. If outside this range, solenoid valve is bad. Replace as needed. Check connections at solenoid to din connector. Check or pushed pins or broken wires between the 12 pin Deutz plug in tank harness to hydraulic control box. Repair as needed.

Troubleshooting Issue & Steps

Values

Results

3. Hydraulic pump will not engage when hose reel or other functions are demanded.

Is there a code logged on the Cat screen for hoist circuit?

If yes, the script file will need to be reloaded into screen software.

Call HOLT Manufacturing to get a copy of this file.



a. **Download and install file** onto a USB thumb drive (3 KB file). Once downloaded, open the file on a Microsoft Windows based computer or laptop. Adjust high and low duty cycles to OEM specs. To obtain these specs, call HOLT Manufacturing, 844-465-8634.

Set tank depth (supplied by HOLT Mfg.) and enable correct number of spray heads by changing spray heads (L1, L2, R1, and R2) to 1 for on and 0 for off.

The water cannon/fire hose will be set to 1 if installed; hose reel will also be set to 1. If gravity bar is installed, set to 1 for on.

When finished, proceed to step b.



b. Load Script into Screen

Once script file is set, load into screen via the USB connection plug in cab harness behind the screen. Install USB memory stick. Screen will go dark for approximately 15 seconds. When screen flashes, remove USB stick. Allow screen to fully boot. This can take up to 1 minute. Once main screen page appears, it is not ready until all side button lights stop flashing and a noticeable brightness appears on the screen. Check to see if the hydraulic operation is back. If not, proceed to step c.

Troubleshooting Issue & Steps

Values

Results

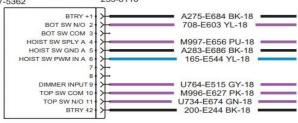


c. Check PWM Signal

Check PWM signal from screen to transmission ECM. The voltage is sent out on pin 4/blue wire at 12 pin Deutz plug on screen. This is a low voltage signal that has two resistors in line, one 1500 ohm and one 500 ohm. See Gilmore diagram for wiring details.

Check resistance on each resistor and continuity to ground. Check connections at shift hoist switch. The pink wire, number M996-E627 (730) is coming out at the hoist switch located directly under the shift lever control has been cut and terminated with a Deutz 2 pin signal wire connector. The other end has a 2 pin signal wire receptacle that the PWM blue wire is connected to. Check each of the male and female connections for pulled wire and plug fit.



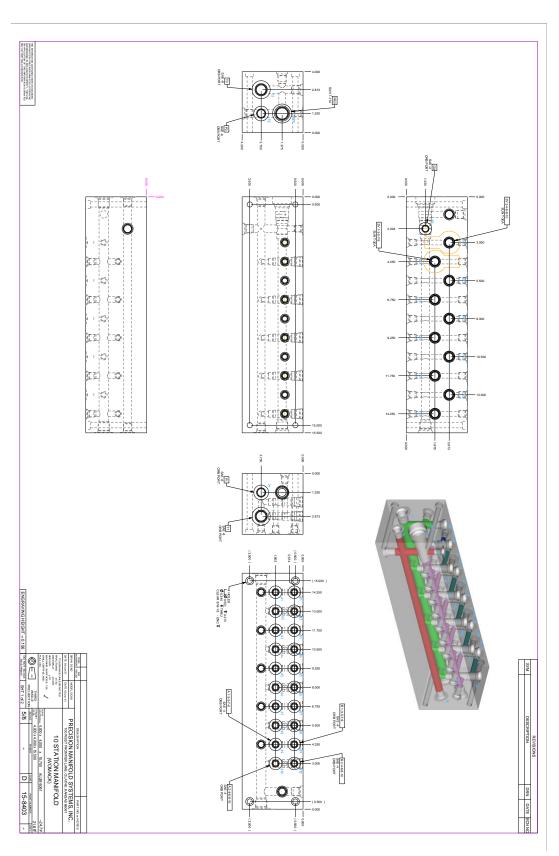


Troubleshooting Issue & Steps	Values	Results
4. Water level reads 0% when tank is	full.	
a. Check LED lights are lit up on water sensor, located on top of tank. If there are no lights, check fuse, located on right side of cab behind outer panel.		Fuse needs replacing. If fuse is OK, proceed to b.
b. If fuse is OK, check voltage at three way connector on sensor harness, located in J box on front of tank. Red wire W11 is 24 volt – check voltage. Black wire W12 is ground; check ground to cab. White wire W19 is output signal to Crossfire control box.		If sensor lights are on, continue to c.
c. If sensor lights are on, check continuity from white wire W19 to pin C to ampseal on Crossfire pin 1. Check for pins pushed back in each connector.		
Changing the depth from the factory setting will cause inaccurate water level readings.		Water level sensor adjustment: Sensor should be extending into tank at the maximum length of sensor threads on some units. It is critical that any replacement sensor be installed at the same depth as the old sensor. This is the setting from the factory installation which is calibrated in the script file.

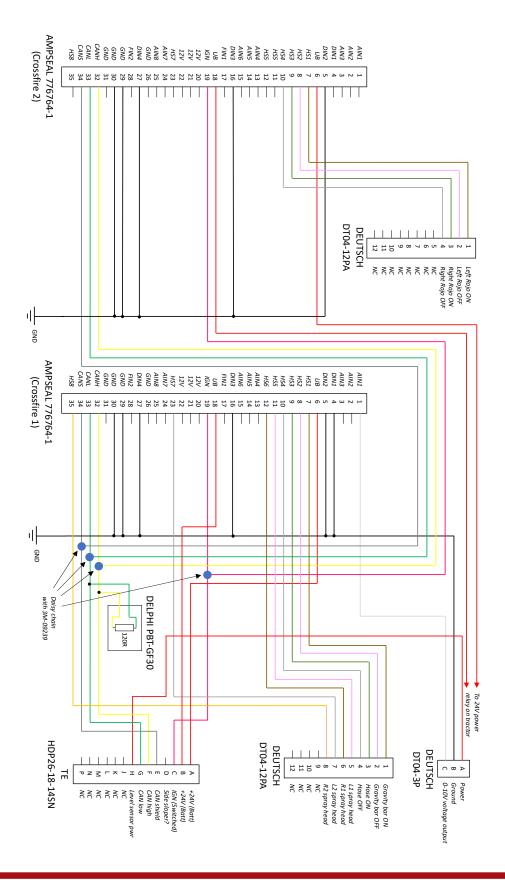
Appendix

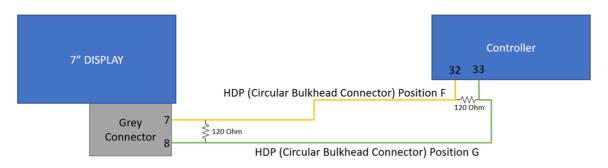
- I. Hydraulic Manifold Diagram
- II. Control Screen Wiring Diagram
- III. Deep Sea Screen Features and Pin Outs
- IV. Nitro Monitor Wiring Diagram
- V. IFM Hydraulic Controller Wiring Diagram

I. Hydraulic Manifold

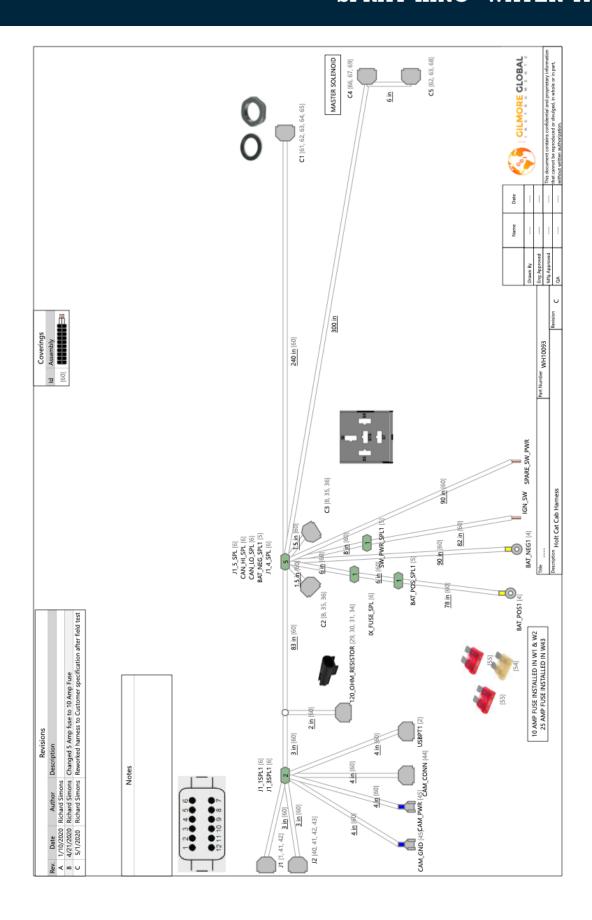


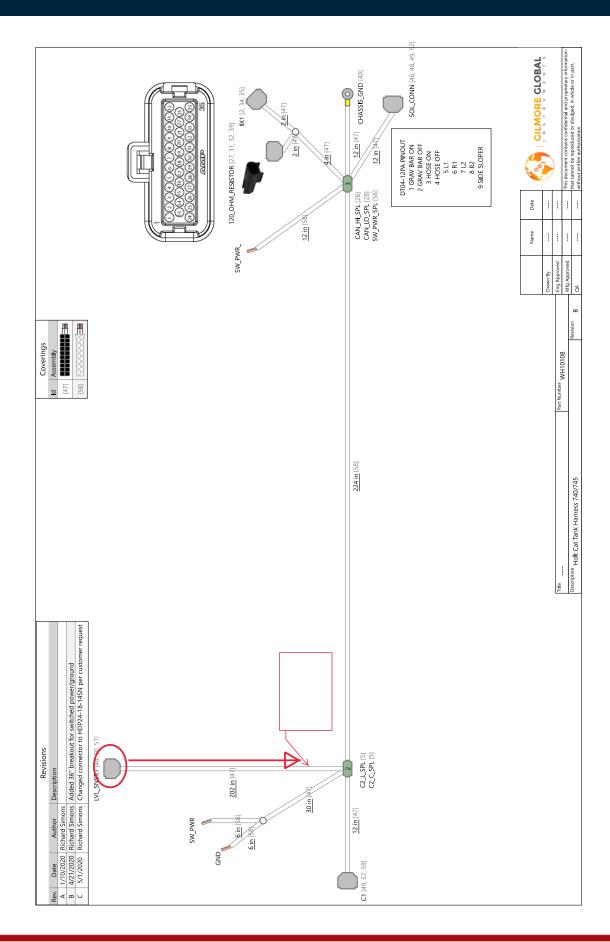
II. Control Screen Wiring Diagram





The yellow wire connects at position F on the HDP connector between the two harnesses, whereas the green wire is located at position G.





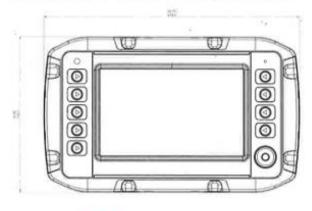
III. Deep Sea Screen Features and Pin Outs





DSEM870

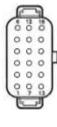
PROGRAMMABLE DISPLAY FOR USE IN VEHICLES AND OFF-HIGHWAY MACHINERY







PRE	DESCRIPTION
1	SGU Bussiy GND
1	CAN GND
3	CHERNO
4	No some weaton
	Carriero 1 (SNI)
	Carrest 3 (950)
ž.	SON Supply -NE
	CAN1 II
8	CANSII
10	Ne pumector
0	Carrens I signal
12	Cerent Zistpel
13	Spreitige + VE (TS)
18	CARTL
18	CMCL
18	No uphreckion
17	No comechan
16	No povrecion



PM	DESCRIPTION	REF
*	Output expety +ME	
1	OUT H. I.	9001
2	QUTHLL	90100
	OUTHIL	9000
1	OUTHU	9000
	WEF -	
7	Ostput swortly GMD	
	Ha connection	
,	November	
10.	7ts careed on	
it	The convention	
12	Ovpu supply GHD	
10	Aut 12 +VE Output	
14	AM-ONH, L.PRID.	1089
10	AM DNH, L. FFED	10000
79	AIN DINH, L. FRED	10000
37	AN, DNH, L, FRED	scans
18.	WHIP OVE	



M12 Or o	nded - 6 ;	pin tema
Per-Et	TK-	1
Per-82	HC+	
PH-EX	16]
PK-91	NO-]



19-05	+3:4:00
No - 08	Date :
fre - 00	Date :
No - 04	40
54 - 05	050

Abbreviations QUT Preme, H, L QUT H, L Abb DNL H, L FREQ A SHO

Coupts, can be configured as a 1990s, PMM, digue high-end or upgate terrusive. Coupt of slight from the configured as anything here or origital low state. Instead on the configured to assess singular from present origint, required upgates deprised. (b.Y to 19 % if milk in 76 milk, subormancy or resistant floors up the configured to accept signate from present argued, registers deprise or insquency. Canada Late received for the reserving major intermals.







-	DSCM870			-
Camera				Connector A
Analogue video input (supported video standards: PAL & NTSC)		2		5, 6, 11, 12
CAN Interfaces				Connector A
Number of CAN ports		2		Pin 2, 3, 8, 9, 14, 15
Supported protocols		J193	9	1
		CAN	open	
		Raw	CAN	
Supported programme	able baud rates		bit/s, 125 kbit/s, 250 s, 500 kbit/s, 800 Mbit/s. sit/s	
Ethernet Interface				M12, 4 pole
Number of Ethernet po	orts	1		D-coded 4 pole socket
Supported data rates		10/1	00 Mbit/s	
Supported protocols		Mod	bus TCP	
		COD	ESYS 3.5	
USB Interface		-		M12, 5 pale
Number of USB host p	ports	11		B-coded, 5 pole socke
Supported USB version	on.	2		
Speeds supported	***	Fulls	speed (12 Mbit/s)	
Device class supporte	d	08.0	Aass Storage)	
Supported filing system	m	FATS	000000000000000000000000000000000000000	
Processor				-
Technexion Freescale	MX6-SOLO Microcontrollar	ARM	1 AD	T
		800	MHz	
Memory		-		1
Flash		2 GE	3	1
RAM		512	MB	
Software				Version
CODESYS 3.5 (M870-01 / M870-02 / M870-03)				SP12 Patch 0
Qt (M870-04)				V 5.15
LED Status				
Colour	Description		Operation	State
None	Device not powered		N/A	Off
Green		Unit powered up, application program loaded but not running Unit powered up, application program loaded and running 1 Hz flash Unit powered up, but no application program loaded 5 Hz flash		Application stopped Application running No application
Amber	Bootloader functioning normally, firmware pre		Static	Bootloader mode
THE STATE OF THE S	C. C	new 1	Static	Section Control of the Control of th
	Firmware is at start-up	Firmware is at start-up		Firmware start-up
	Unit stopped due to a serious fault	Unit stopped due to a serious fault		Application exception
	Bootloader is decrypting the downloaded ima	Shortlander is decompling the downloaded maps		Decrypting image
	Bootloader is reading an image from the USB		1 Hz flash 5 Hz flash	Reading image from USB
Red	Fatal system/hardware fault - LEd may be dri microcontroller error pin or firmware is in a fa		Static	Fatal error
	Unit running with a fault, see CDDESYS over or web tool.	flags	1 Hz flash	Faulty application running

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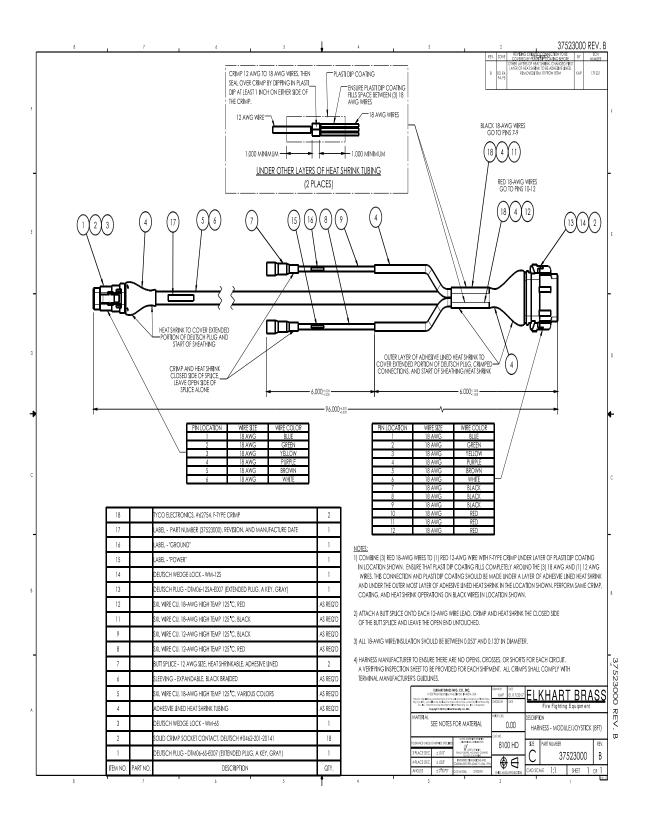


Technical Data

Supply		Comments A
The state of the s	AMBON MANDO	Connector A
Operating voltage	8 V DC to 32 V DC	Pin 7
Unit power supply maximum current consumption, full backlight (no external loads)	< 1000 mA at 12 V and 24 V	
Unit power supply maximum current consumption, full backlight and heater (no external loads)	< 1500 mA at 12 V and 24 V	
Unit power supply current consumption after controlled shutdown has occurred due to the lightion being turned off	< 5 mA at 24 V	
Fusing		Connector A
Unit power supply external protection fuse rating	3 A	Pin 7
High current outputs supply input external fuse protection rating (i.e., sum of output currents from all outputs provided for by an individual supply to < external fuse rating in total)	10 A	Pin 1
Housing		
PC PBT alloy plastic resin		
Dimensions		
140 mm x 230 mm x 60 mm (W x H x D) / 10.8° x 6.3° x 3.15° (W x H x D)		
Weight		
< 1 kg		
Temperature		
Operating temperature	-30 °C to +85 °C / -22 °F to +185 °F	
Storage temperature	+40 ° C to +85 °C / -40 ° F to +185 ° F	
Protection Rating		
	IP67 (with mating connectors)	
Display	-	
Resolution, pixel	800 px x 480 px	
Colour	24 bit	
Format	7' diagonal	
Touchscreen	Capacitive touch (M870-02 / M870-04 variants)	
Mounting	Optically bonded	
llumination	LED (ifetime > 50,000 trs)	
Connectors	tota grantini z supun maj	
Connector A	18 pin TE connectivity DT16- 18SA-K004	
Connector C	18 pin TE connectivity DT16- 18SC-K004	
Ethernet	M12, D-coded 4 pole socket	
US8	M12, B-coded 5 pale socket	
Digital Inputs		Connector C
Digital inputs configured high or low		Pin 14, 15, 16, 11
High level voltage threshold	> 6 V	
Low level voltage threshold	<2V	
Analogue Voltage inputs	177775	Connector C
0 V to 5 V programmable voltage range	0 V to 5 V	Pin 14, 15, 16, 1
0 V to 10 V programmable voltage range	0 V to 10 V	
0 V to 32 V programmable voltage range	0 V to 32 V	
Voltage measurement resolution	12 bils	
Voltage measurement accuracy	± 1% FSD	
Voltage measurement input resistance	≥ 30 kt2	
Voltage measurement sampling rate	500 Hz	
FSD = Full Scale Deflection	1554.06	

068-199/03/21 (A)

IV. Nitro Monitor Wiring Diagram



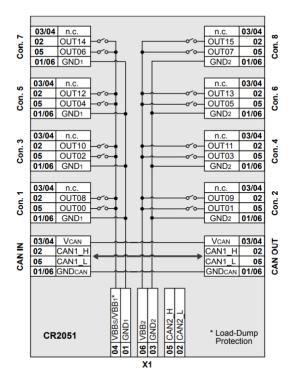
V: IFM Controller Wiring Diagram

CR2051 - GUIDE TO HOLT/GGI SOFTWARE

1.1 Pin Configuration

The 16 outputs of the CR2051 are distributed between the 6-pin Deutsch connectors There are two outputs on each connector. There are ground terminals allocated in the connector but not specifically used as we use the chassis ground directly in the wire design.

Given below is the pinout for the controller.



1.2 Troubleshooting Wiring

A few scenarios that could happen in case of bad contacts from wiring:

- CR2051 does not power on: Check that terminals 1,4,6,3 on connector X1 are all connected to ignition
 power and ground appropriately. Pins 1 and 4 are the main power supply, and pins 3 and 6 provide power
 for specific outputs to function properly.
- Controller does not respond to the state of the Deep Sea/ DSE M870: Ensure that the CAN bus wires make good contact individually on both sides. Further, make sure that the CAN HI and CAN LO have a resistance of $60~\Omega$ with all parts of the harness connected, and $120~\Omega$ with the parts being disconnected. The resistances are near the device and thus the intermediate harness will be an open connection between CAN HI and CAN LO bus lines.
- CR2051 LEDs light up but do not activate some or all the valves: Make sure that there is solid connection between the valve and the designated output, and that there is a good ground on the valve's second terminal.

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Additionally, verify that both the power and ground lines on X1 connector have good connections. It is possible that the CR2051 is powered by just one line, in which case the device will fail to supply power to half the outputs.

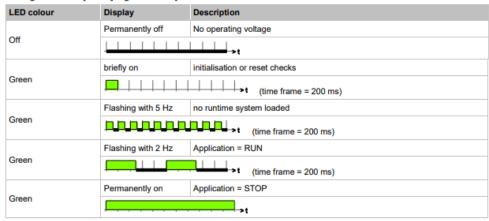
☐ CR2051 seems to power on but the built-in display does not work: Check the power lines and make sure all the ignition power and grounds are connected. Additionally check if the LEDs on the CR2051 (located just above the 4-digit display) are in any error state.

LED Description:

There are a total of 6 LEDs located just above the 4-digit display. From left to right these are: LED [Power](green), LED [Mode](green), Application LEDs(green), LED [Lock] (green), LED [Diagnostics] (red)

Only LED [Power] and LED [Diagnostics] are used to convey the system status and errors:

The green LED [PWR] signals the system status.



The red LED [DIA] signals the diagnostic status.

LED colour	Display	Description		
	Permanently off	No operating voltage		
Off				
	briefly on	initialisation or reset checks		
Red	t (time frame = 200 ms)			
Red	Flashing with 10 Hz	Application = STOP with error application program is stopped Cause: exceeded timeout of the application or visualisation: ▶ Delete the application! ▶ PowerOn reset ▶ Reload the application into the device		
	time frame = 200 ms)			
Flashing with 5 Hz Application		Application = stopped because of undervoltage		
Red	(time frame = 200 ms)			
Red	Permanently on	System error (FATAL ERROR): Application = STOP		
		· · · · →t		

1.3. Device Description and Configuration

The CR2051 has 16 outputs in total, labeled OUT00 to OUT15. Each output is mapped to specific purpose, either single acting or complementary double acting solenoid. 6 of the outputs are single acting, and 8 outputs are committed towards 4 double acting solenoids in total.

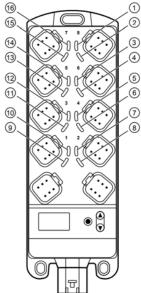
Given here is an illustration of the LEDs on the device, and the mapped output for each.

The LEDs are operational for all 16 outputs regardless of the type of solenoid being used.

If the LED is lit, the corresponding output is at 12/24V state.

In the Holt specific software, the PWM output's LED is lit up when the master solenoid is switched on, or the PWM duty cycle is at the configured high state.





1.4. Mapped Outputs to Holt-Specific Purpose

OUTPUT	PURPOSE
OUT00	GravBar1
OUT01	GravBar2
OUT02	FireHose1
OUT03	FireHose2
OUT04	L1
OUT05	R1
OUT06	L2
OUT07	R2
OUT08	LRojo1
OUT09	LRojo2
OUT10	RRojo1
OUT11	RRojo2
OUT12	L3
OUT13	R3
OUT14	Not Used
OUT15	PWM MasterSolenoid

2.1. Display Output

The default display on the CR2051 signifies the most up to date output status requested on the CAN bus.It is a hexadecimal number that corresponds to the 16 outputs on the device. Each character in the string describes the state of 4 outputs in order.

The most significant bit (left side) points to OUT15 and the least significant bit (right side) points to OUT00. On startup, the status will show 0000, or all off.

Few examples from the 256 possibilities of the statuses:

Status	OUT															
	15	14	13	12	11	10	09	80	07	06	05	04	03	02	01	00
FFFF	<	\	✓	✓	✓	\	✓	<	✓	✓	>	<	✓	✓	✓	<
0000																
0100								<								
A001	\		✓													✓
05C0						\		✓	✓	✓						

✓- The output is high, or at 12/24V. This does not reflect valve state.

The same can also be verified with the amber LEDs beside each output, as shown in the diagram before.

2.2. Convenient way to decode the 4-digit display

Since the 4-digit display represents the output state in hexadecimal, an online converter, or a calculator with such features can be used to decode the string to get the current state easily.

For example, using the calculator built into Windows 10 and for the string A001:

- 1. Open the calculator application and switch to Programmer mode from the navigation drawer.
- 2. Click on "HEX" from the four options.
- 3. Type the string. In this case it is "A001".
- 4. Check the equivalent number in binary which will be under "BIN" and will update as you type the hexadecimal number.
- 5. The binary number represents 1 for +24/12V and 0 for off state. Read this number from right to left to match the outputs from OUT00 to OUT15. If there are less than 16 digits in the binary number, the other outputs are 0.

